



Contents lists available at ScienceDirect

Journal of Econometrics

journal homepage: [www.elsevier.com/locate/jeconom](http://www.elsevier.com/locate/jeconom)

## Predictable returns and asset allocation: Should a skeptical investor time the market?<sup>☆</sup>

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### ARTICLE INFO

#### Article history:

Received 29 May 2007

Received in revised form

16 September 2008

Accepted 16 October 2008

Available online 5 November 2008

### ABSTRACT

We investigate optimal portfolio choice for an investor who is skeptical about the degree to which excess returns are predictable. Skepticism is modeled as an informative prior over the  $R^2$  of the predictive regression. We find that the evidence is sufficient to convince even an investor with a highly skeptical prior to vary his portfolio on the basis of the dividend-price ratio and the yield spread. The resulting weights are less volatile and deliver superior out-of-sample performance as compared to the weights implied by an entirely model-based or data-based view.

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### 0. Introduction

Are excess returns predictable, and if so, what does this mean for investors? In classic studies of rational valuation (e.g. Samuelson (1965, 1973) and Shiller (1981)), risk premia are constant over time and thus excess returns are unpredictable.<sup>2</sup> However, an extensive empirical literature has found evidence for predictability in returns on stocks and bonds by scaled-price ratios and interest rates.<sup>3</sup>

<sup>☆</sup> For helpful comments, we thank the associate editor and two anonymous referees, as well as John Campbell, John Cochrane, Joel Dickson, Itamar Drechsler, Bjorn Eraker, John Geweke, Martin Lettau, Stijn Van Nieuwerburgh, Lubos Pastor, Jay Shanken, Robert Stambaugh, Alexander Stremme, Ivo Welch, Amir Yaron, Motohiro Yogo and seminar participants at the 2005 CIRANO-CIREQ Financial Econometrics Conference, the 2006 AFA meetings, the 2006 SED meetings, the 2007 D-CAF Conference on Return Predictability, and at Harvard University, the Vanguard Group, and the Wharton School. We are grateful for financial support from the Aronson + Johnson + Ortiz fellowship through the Rodney L. White Center for Financial Research. This manuscript does not reflect the views of the Board of Governors of the Federal Reserve System.

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<sup>2</sup> Examples of general-equilibrium models that imply excess returns that are largely unpredictable include Abel (1999, 1990), Backus et al. (1989), Campbell (1986), Cecchetti et al. (1993), Kandel and Stambaugh (1991) and Mehra and Prescott (1985).

<sup>3</sup> See, for example, Fama and Schwert (1977), Keim and Stambaugh (1986), Campbell and Shiller (1988), Fama and French (1989), Cochrane (1992), Goetzmann and Jorion (1993), Hodrick (1992), Kothari and Shanken (1997), Lettau and Ludvigson (2001), Lewellen (2004) and Ang and Bekaert (2007).

Confronted with this theory and evidence, the literature has focused on two polar viewpoints. On the one hand, if models such as Samuelson (1965) are correct, investors should maintain constant weights rather than form portfolios based on possibly spurious evidence of predictability. On the other hand, if the empirical estimates capture population values, then investors should time their allocations to a large extent, even in the presence of transaction costs and parameter uncertainty.<sup>4</sup> Between these extremes, however, lies an interesting intermediate view: that both data and theory can be helpful in forming portfolio allocations.

This paper models this intermediate view in a Bayesian setting. We consider an investor who has a prior belief about the  $R^2$  of the predictive regression. We implement this prior by specifying a normal distribution for the regression coefficient on the predictor variable. As the variance of this normal distribution approaches zero, the prior belief becomes dogmatic that there is no predictability. As the variance approaches infinity, the prior is diffuse: all levels of predictability are equally likely. In between, the distribution implies that the investor is skeptical about predictability: predictability is possible, but it is more likely that

<sup>4</sup> See, for example, Brennan et al. (1997) and Campbell and Viceira (1999) for stocks and Sangvinatsos and Wachter (2005) for long-term bonds. Balduzzi and Lynch (1999) show that predictability remains important even in the presence of transaction costs, while Barberis (2000) and Xia (2001) show, respectively, that predictability remains important in the presence of estimation risk and learning. An exception is the case of buy-and-hold portfolios with horizons of many years (Barberis, 2000; Cochrane, 1999; Stambaugh, 1999). Brennan and Xia (2005) construct a long-run measure of expected returns and derive implications for optimal portfolios. They show that this long-run measure often implies a less extreme response to predictability than regression-based measures.

predictability is “small” rather than “large”. By conditioning this normal distribution on both the unexplained variance of returns and on the variance of the predictor variable, we create a direct mapping from the investor’s prior beliefs on model parameters to a well-defined prior over the  $R^2$ .

In our empirical implementation, we consider returns on a stock index and on a long-term bond. The predictor variables are the dividend-price ratio and the yield spread between Treasuries of different maturities. We find that the evidence is sufficient to convince an investor who is quite skeptical about predictability to vary his portfolio on the basis of these variables. The resulting weights, however, are much less volatile than for an investor who allocates his portfolio purely based on data. To see whether the skeptical prior would have been helpful in the observed time series, we implement an out-of-sample analysis. We show that weights based on skeptical priors deliver superior out-of-sample performance when compared with diffuse priors, dogmatic priors, and to a simple regression-based approach.

Our study builds on previous work that has examined predictability from a Bayesian investment perspective. Kandel and Stambaugh (1996) show that predictive relations that are weak in terms of standard statistical measures can nonetheless affect portfolio choice.<sup>5</sup> They conduct a simulation experiment such that predictability is present with modest significance, and examine the portfolio choices of a Bayesian investor who views the simulated data. In contrast, our study bases its inference on the historical time series of returns and predictor variables. We ask whether an investor whose priors imply skepticism about the existence of predictability would find it optimal to vary their investments in risky assets over time. Other studies make use of informative priors in a setting of return predictability. Avramov (2002) and Cremers (2002) show that Bayesian inference and informative priors can lead to superior model selection. Shanken and Tamayo (2005) jointly model time variation in risk and expected return in a Bayesian setting. Shanken and Tamayo incorporate model-based intermediate views on the relation between expected return and risk. In what follows, we compare the prior beliefs we assume to those in each of these related studies.

Our study is also related to that of Poirier (1996), who calculates the prior distribution on the  $R^2$  that is implied by the prior distributions on the regression coefficients and on the standard deviation of errors. Poirier points out that it is often easier to elicit priors on goodness-of-fit measures, such as the  $R^2$ , as compared to priors on the regression coefficients. Our motivation for using the  $R^2$  is similar. Our study differs from that of Poirier’s in that we assume a time-series setting in which the regressors are not predetermined. We also explicitly calculate the implied posteriors and develop the implications for portfolio choice.

Our use of model-based informative priors has parallels in a literature that examines the portfolio implications of the cross-section of stock returns. Motivated by the extreme weights and poor out-of-sample performance of mean-variance efficient portfolios (Best and Grauer, 1991; Green and Hollifield, 1992), Black and Litterman (1992) propose using market weights as a benchmark, in effect using both data and the capital asset

pricing model to form portfolios. Recently, Bayesian studies such as Pastor (2000), Avramov (2004) and Wang (2005) construct portfolios incorporating informative beliefs about cross-sectional asset pricing models.<sup>6</sup> Like the present study, these studies show that allowing models to influence portfolio selection can be superior to using the data alone. While these studies focus on the cross-section of returns, we apply these ideas to the time series.

The remainder of this paper is organized as follows. Section 1 describes the assumptions on the likelihood and prior, the calculation of the posterior, and the optimization problem of the investor. Section 2 applies these results to data on stock and bond returns, describes the posterior distributions, the portfolio weights, and the out-of-sample performance across different choices of priors. Section 3 concludes.

## 1. Portfolio choice for a skeptical investor

Given observations on returns and a predictor variable, how should an investor allocate his wealth? One approach would be to estimate the predictability relation, treat the point estimates as known, and solve for the portfolio that maximizes utility. An alternative approach, adopted in Bayesian studies, is to specify prior beliefs on the parameters. The prior represents the investor’s beliefs about the parameters before viewing data. After viewing data, the prior is updated to form a posterior distribution; the parameters are then integrated out to form a predictive distribution for returns, and utility is maximized with respect to this distribution. This approach incorporates the uncertainty inherent in estimation into the decision problem (see Klein and Bawa (1976), Bawa et al. (1979) and Brown (1979)).<sup>7</sup> Rather than assuming that the investor knows the parameters, it assumes, realistically, that the investor estimates the parameters from the data. Moreover, this approach allows for prior information, perhaps motivated by economic models, to enter into the decision process. This section describes the specifics of the likelihood function, the prior, and the posterior used in this study.

### 1.1. Likelihood

This subsection constructs the likelihood function. Let  $r_{t+1}$  denote an  $N \times 1$  vector of returns on risky assets in excess of a riskless asset from time  $t$  to  $t + 1$ , and  $x_t$  a scalar predictor variable at time  $t$ . The investor observes data on returns  $r_1, \dots, r_T$ , and the predictor variable  $x_0, \dots, x_T$ . Let

$$D \equiv \{r_1, \dots, r_T, x_0, x_1, \dots, x_T\}$$

represent the total data available to the investor. Our initial assumption is that there is a single predictor variable that has the potential to predict returns on (possibly) multiple assets. Allowing multiple predictor variables complicates the problem without contributing to the intuition. For this reason, we discuss the case of multiple predictor variables in Appendix A.

The data generating process is assumed to be

$$r_{t+1} = \alpha + \beta x_t + u_{t+1} \quad (1)$$

$$x_{t+1} = \theta_0 + \theta_1 x_t + v_{t+1}, \quad (2)$$

<sup>5</sup> Subsequently, a large literature has examined the portfolio consequences of return predictability in a Bayesian framework. Barberis (2000) considers the optimization problem of a long-horizon investor when returns are predictable. Xia (2001) considers the effect of learning about the predictive relation in a dynamic setting with hedging demands. Brandt et al. (2005) and Skoulakis (2007) extend this work to allow for uncertainty and learning about the other parameters in the predictive system. Johannes et al. (2002) model the mean and volatility of returns as latent factors. Our methods build directly on those of Stambaugh (1999), who studies the impact of changes in the prior and changes in the likelihood. In contrast to the present study, these papers assume diffuse priors.

<sup>6</sup> Related approaches to improving performance of efficient portfolios include Bayesian shrinkage (Jobson and Korkie, 1980; Jorion, 1985) and portfolio constraints (Frost and Savarino, 1988; Jagannathan and Ma, 2003). Cvitanić et al. (2006) incorporate analyst forecasts in a dynamic setting with parameter uncertainty and learning. Garlappi et al. (2007) take a multi-prior approach to portfolio allocation that allows for ambiguity aversion. Tu and Zhou (2007) impose priors that ensure that portfolio weights fall into a certain range. Unlike the present study, these papers assume that the true distribution of returns is iid and focus on the cross-section.

<sup>7</sup> Like these papers and like the portfolio choice papers cited in the introduction, this paper studies an investor who should not be viewed as representative. By definition, the representative investor must hold the market portfolio.

where

$$\begin{bmatrix} u_{t+1} \\ v_{t+1} \end{bmatrix} | r_t, \dots, r_1, x_t, \dots, x_0 \sim N(0, \Sigma), \tag{3}$$

$\alpha$  and  $\beta$  are  $N \times 1$  vectors and  $\Sigma$  is an  $(N + 1) \times (N + 1)$  symmetric and positive definite matrix.<sup>8</sup> It is useful to partition  $\Sigma$  so that

$$\Sigma = \begin{bmatrix} \Sigma_u & \Sigma_{uv} \\ \Sigma_{vu} & \Sigma_v \end{bmatrix},$$

where  $\Sigma_u$  is the variance–covariance matrix of  $u_{t+1}$ ,  $\sigma_v^2 = \Sigma_v$  is the variance of  $v_{t+1}$ ,  $\Sigma_{uv}$  is the  $N \times 1$  vector of covariances of  $v_{t+1}$  with each element of  $u_{t+1}$ , and  $\Sigma_{vu} = \Sigma_{uv}^\top$ . This likelihood is a multi-asset analogue of that assumed by Kandel and Stambaugh (1996) and Campbell and Viceira (1999), and many subsequent studies.

It is helpful to group the regression parameters in (1) and (2) into a matrix:

$$B = \begin{bmatrix} \alpha^\top & \theta_0 \\ \beta^\top & \theta_1 \end{bmatrix},$$

and to define matrices of the observations on the the left hand side and right hand side variables:

$$Y = \begin{bmatrix} r_1^\top & x_1 \\ \vdots & \vdots \\ r_T^\top & x_T \end{bmatrix}, \quad X = \begin{bmatrix} 1 & x_0 \\ \vdots & \vdots \\ 1 & x_{T-1} \end{bmatrix}.$$

As shown in Barberis (2000) and Kandel and Stambaugh (1996), the likelihood conditional on the first observation takes the same form as in a regression model with non-stochastic regressors. Let  $p(D|B, \Sigma, x_0)$  denote the likelihood function. From results in Zellner (1996), it follows that

$$p(D|B, \Sigma, x_0) = |2\pi \Sigma|^{-\frac{T}{2}} \exp \left\{ -\frac{1}{2} \text{tr} [(Y - XB)^\top (Y - XB) \Sigma^{-1}] \right\}, \tag{4}$$

where  $\text{tr}(\cdot)$  denotes the sum of the diagonal elements of a matrix.<sup>9</sup>

The likelihood function (4) conditions on the first observation of the predictor variable,  $x_0$ . In contrast, observations  $1, \dots, T$  are treated as draws from the data-generating process. An alternative, implemented in a return-predictability setting by Stambaugh (1999), is to treat  $x_0$  as a draw from the data-generating process as well. The resulting likelihood function fully incorporates the information contained in  $x_0$ , while (4) does not. It may at first seem that this choice should make little difference, since only one observation is involved. However, Poirier (1978) shows that the consequences can be quite substantial because the first observation is transformed in a different way than the remaining observations.

In constructing the likelihood that does not condition on  $x_0$ , we assume that the process for  $x_t$  is stationary and has run for a substantial period of time. Results in Hamilton (1994, p. 53) imply that  $x_0$  is a draw from a normal distribution with mean

$$\mu_x \equiv E[x_t | B, \Sigma] = \frac{\theta_0}{1 - \theta_1} \tag{5}$$

<sup>8</sup> Results assuming a multivariate  $t$ -distribution are similar to those reported below and available from the authors upon request.

<sup>9</sup> Maximizing the conditional likelihood function (4) implies estimates of  $\beta$  that are the same as those obtained by ordinary least squares regression. These estimates are biased (see Bekaert et al. (1997), Nelson and Kim (1993) and Stambaugh (1999)), and standard asymptotics provide a poor approximation to the distribution of test statistics in small samples (Cavanagh et al., 1995; Elliott and Stock, 1994; Mankiw and Shapiro, 1986; Richardson and Stock, 1989). An active literature based in classical statistics focuses on correcting for these problems (e.g. Amihud and Hurvich (2004), Campbell and Yogo (2006), Elias (2004), Ferson et al. (2003), Lewellen (2004) and Torous et al. (2004)).

and variance

$$\sigma_x^2 \equiv E[(x_t - \mu_x)^2 | B, \Sigma] = \frac{\sigma_v^2}{1 - \theta_1^2}. \tag{6}$$

Combining the likelihood of the first observation with the likelihood of the remaining  $T$  observations produces

$$\begin{aligned} p(D|B, \Sigma) &= p(D|x_0, B, \Sigma)p(x_0|B, \Sigma) \\ &= (2\pi\sigma_x^2)^{-\frac{1}{2}} |2\pi \Sigma|^{-\frac{T}{2}} \exp \left\{ -\frac{1}{2}\sigma_x^{-2} (x_0 - \mu_x)^2 \right. \\ &\quad \left. - \frac{1}{2} \text{tr} [(Y - XB)^\top (Y - XB) \Sigma^{-1}] \right\}. \end{aligned} \tag{7}$$

Eq. (7) is the likelihood function used in our analysis. Following Box et al. (1970), we refer to (7) as the exact likelihood, and to (4) as the conditional likelihood.

### 1.2. Prior beliefs

This subsection describes the prior. We specify prior distributions that range from being “uninformative” in a sense we will make precise, to “dogmatic”. The uninformative priors imply that all amounts of predictability are equally likely, while the dogmatic priors rule out predictability all together. Between these extremes lie priors that downweight empirical evidence on return predictability. These informative priors imply that large values of the  $R^2$  from predictive regressions are unlikely, but not impossible.

Before discussing the specifics of our informative priors, we briefly discuss how asset-pricing theory guides us toward these priors. Models with constant relative risk aversion, rational agents, and homoskedastic endowments (e.g. Abel (1990, 1999), Backus et al. (1989) and Barro (2006) and the benchmark case in Bansal and Yaron (2004)) imply that the  $R^2$  in the predictability regression is exactly zero.<sup>10</sup> Recently, several papers propose general equilibrium models that are capable of generating time-varying expected excess returns (risk premia). Models that successfully account for time-varying risk premia have done so through one of several mechanisms: time-varying relative risk aversion (e.g. Campbell and Cochrane (1999)), non-rational investors (e.g. Barberis et al. (2001)), or time-varying volatility in the endowment process (e.g. Whitelaw (2000) and Bansal and Yaron (2004)). An investor whose prior is that constant relative risk aversion is more likely than time-varying relative risk aversion, that investors are more likely to be rational and that aggregate consumption growth is more likely to be homoskedastic would therefore place low probability on a high  $R^2$  from predictive regressions.<sup>11</sup>

<sup>10</sup> Models with regime shifts in the endowment process, such as Cecchetti et al. (1993), Kandel and Stambaugh (1991), Mehra and Prescott (1985) and Reitz (1988) imply a small amount of heteroskedasticity, and therefore of excess return predictability. The amount of excess return predictability generated through the regime-shift mechanism is very small, however. Allowing for this small amount of predictability in the prior would greatly complicate the analysis and is unlikely to affect the results.

<sup>11</sup> Of these possibilities, it is perhaps most difficult to conceptualize a prior over endowment heteroskedasticity. This issue is complicated by the fact that a model with endowment heteroskedasticity will not necessarily imply that return heteroskedasticity takes a simple form, and that return variance and risk premia are related in a straightforward way. In a study that we discuss further below, Shanken and Tamayo (2005) take a reduced-form approach and assume priors that favor a linear relation between the return variance and the risk premium. They find that there is significant variation in expected excess returns that does not correspond to variation in volatility, a conclusion also reached in many frequentist studies (see Campbell (2003) for a survey). We hope to investigate the important issue of heteroskedasticity in future research; however, given the results of existing studies we expect our conclusions to be unaffected.

We now discuss the specific form assumed for the investor's prior beliefs. The most obvious parameter that determines the degree of predictability is  $\beta$ . Set  $\beta$  to zero, and there is no predictability in the model. However, it is difficult to think of prior beliefs about  $\beta$  in isolation from beliefs about other parameters. For example, a high variance of  $x_t$  might lower one's prior on  $\beta$ , while a large residual variance of  $r_t$  might raise it. Rather than placing a prior on  $\beta$  directly, we instead place a prior on "normalized"  $\beta$ , that is  $\beta$  adjusted for the variance of  $x$  and the variance of  $u$ . As we show below, this is equivalent to placing a prior on the population equivalent of the centered, unadjusted  $R^2$ . Let  $C_u$  be the Cholesky decomposition of  $\Sigma_u$ , i.e.  $C_u C_u^\top = \Sigma_u$ . Then

$$\eta = C_u^{-1} \sigma_x \beta$$

is normalized  $\beta$ . We assume that prior beliefs on  $\eta$  are given by

$$\eta \sim N(0, \sigma_\eta^2 I_N), \tag{8}$$

where  $I_N$  is the  $N \times N$  identity matrix.<sup>12</sup>

We implement the prior for  $\eta$  by specifying a hierarchical prior for the primitive parameters. That is, the prior for  $\beta$  is conditional on the remaining parameters:

$$p(B, \Sigma) = p(\beta|\alpha, \theta_0, \theta_1, \Sigma)p(\alpha, \theta_0, \theta_1, \Sigma). \tag{9}$$

Then the specification for the distribution for  $\eta$ , (8), is equivalent to the following specification for the distribution of  $\beta$ :

$$\beta|\alpha, \theta_0, \theta_1, \Sigma \sim N(0, \sigma_\eta^2 \sigma_x^{-2} \Sigma_u). \tag{10}$$

Because  $\sigma_x$  is a function of  $\theta_1$  and  $\sigma_v$ , the prior on  $\beta$  is also implicitly a function of these parameters.

For the remaining parameters, we choose a prior that is uninformative in the sense of Jeffreys (1961).<sup>13</sup> We follow the approach of Stambaugh (1999) and Zellner (1996), and derive a limiting Jeffreys prior as explained in Appendix D. This limiting prior takes the form

$$p(\alpha, \theta_0, \theta_1, \Sigma) \propto \sigma_x |\Sigma_u|^{1/2} |\Sigma|^{-\frac{N+4}{2}}, \tag{11}$$

for  $\theta_1 \in (-1, 1)$ , and zero otherwise. Therefore the joint prior is given by

$$p(B, \Sigma) = p(\beta|\alpha, \theta_0, \theta_1, \Sigma)p(\alpha, \theta_0, \theta_1, \Sigma) \propto \sigma_x^{N+1} |\Sigma|^{-\frac{N+4}{2}} \exp \left\{ -\frac{1}{2} \beta^\top (\sigma_\eta^2 \sigma_x^{-2} \Sigma_u)^{-1} \beta \right\}. \tag{12}$$

Note that in (11) and (12),  $\sigma_x$  is a nonlinear function of the autoregressive coefficient  $\theta_1$  and volatility of the shock to the predictor variable  $\sigma_v$ .

The appeal of linking the prior distribution of  $\beta$  to the distribution of  $\Sigma_u$  and  $\sigma_x$  is that it implies a well-defined distribution on the population  $R^2$ . Consider for simplicity the case

of a single risky asset. In population, the ratio of the variance of the predictable component of return to the total variance is equal to

$$R^2 = \beta^2 \sigma_x^2 (\beta^2 \sigma_x^2 + \Sigma_u)^{-1} = \frac{\eta^2}{\eta^2 + 1}. \tag{13}$$

(note that  $\Sigma_u$  is a scalar). Eq. (13) is the population equivalent of the centered, unadjusted  $R^2$ . In what follows, we will refer to (13) simply as the  $R^2$ . Because the  $R^2$  is a function of  $\eta$  alone, specifying a prior on  $\eta$ , and therefore specifying the joint prior (12), implies a well-defined prior distribution on the  $R^2$ .

When there are  $N$  risky assets, there is a natural extension of (13). Besides implying a distribution on the  $R^2$  of each asset, the distribution of  $\eta$ , (8) implies a joint distribution such that no linear combination of asset returns can have an  $R^2$  that is "too large". To be more precise, let  $w$  be an  $N \times 1$  vector. Then calculations in Appendix B show that

$$\begin{aligned} \max_w R^2 &= \max_w \frac{w^\top \beta \beta^\top \sigma_x^2 w}{w^\top \beta \beta^\top w \sigma_x^2 + w^\top \Sigma_u w} \\ &= \frac{\eta^\top \eta}{\eta^\top \eta + 1}. \end{aligned} \tag{14}$$

The return on the risky part of an investor's portfolio is a linear combination of the returns on the risky assets; therefore the risky part of any portfolio chosen by the investor must have an  $R^2$  that lies below (14). An alternative strategy would be to link the prior to the  $R^2$  of the optimal portfolio of the investor. However, this optimal portfolio depends not only on the history of the data, it also depends on the particular value of the predictor variable. Both are unknown to the investor when forming the prior. In contrast, placing a prior on the  $R^2$ , or on the maximum  $R^2$  of a system of equations, has simple, intuitive appeal.<sup>14</sup>

Fig. 1 depicts the distribution of the  $R^2$  implied by these prior beliefs. The figure shows the probability that the  $R^2$  exceeds some value  $k$ ,  $P(R^2 \geq k)$ , as a function of  $k$ ; it is therefore one minus the cumulative distribution function for the  $R^2$ . We construct this figure by simulating draws of  $\eta$  from (8) and, for each draw, constructing a draw from the  $R^2$  distribution using (13). As this figure shows, the parameter  $\sigma_\eta$  indexes the degree to which the prior is informative. For  $\sigma_\eta = 0$ , the investor assigns zero probability to a positive  $R^2$ ; for this reason  $P(R^2 \geq k)$  is equal to one at zero and is zero elsewhere. As  $\sigma_\eta$  increases, the investor assigns non-zero probability to positive values of the  $R^2$ . For  $\sigma_\eta = 0.04$ , the probability that the  $R^2$  exceeds 0.02 is 0.0005. For  $\sigma_\eta = 0.08$ , the probability that the  $R^2$  exceeds 0.02 is 0.075. Finally when  $\sigma_\eta$  is large, approximately equal probabilities are assigned to all values of the  $R^2$ . This is the diffuse prior that expresses no skepticism with regard to the data. In what follows, we will consider the implications of these four priors for the individual's investment decisions. We will refer to them by using the corresponding probabilities that the  $R^2$  exceeds 0.02. We note, however, that we focus on 0.02 for convenience; any number between 0 and 1 could be substituted.

<sup>12</sup> Formally, we can consider a prior on the parameters  $p(\alpha, \eta, \theta_0, \theta_1, \Sigma) = p(\eta)p(\alpha, \theta_0, \theta_1, \Sigma)$ , where  $p(\eta)$  is defined by (8).

<sup>13</sup> The notion of an uninformative prior in a time-series setting is a matter of debate. One approach is to ignore the time-series aspect of (1) and (2), treating the right hand side variable as exogenous. This implies a flat prior for  $\alpha, \beta, \theta_0$ , and  $\theta_1$ . When applied in a setting with exogenous regressors, this approach leads to Bayesian inference which is quite similar to classical inference (Zellner, 1996). However, Sims and Uhlig (1991) show that applying the resulting priors in a time series setting leads to different inference than classical procedures when  $x_t$  is highly persistent. As a full investigation of these issues is outside the scope of this study, we focus on the Jeffreys prior. Replacing the prior in (11) with one that is implied by exogenous regressors gives results that are similar to our current ones; these are available from the authors.

<sup>14</sup> This prior distribution could easily be modified to impose other restrictions on the coefficients  $\beta$ . In the context of predicting equity returns, Campbell and Thompson (2008) suggest disregarding estimates of  $\beta$  if the expected excess return is negative, or if  $\beta$  has an opposite sign to that suggested by theory. In our model, these restrictions could be imposed by assigning zero prior weight to the appropriate regions of the parameter space. One could also consider a non-zero mean for  $\beta$ , corresponding to a prior belief that favors predictability of a particular sign. For simplicity, we focus on priors that apply to any predictor variable on possibly multiple assets, and leave these extensions to future work.

























